

# Message Passing Model

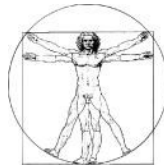
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- Message Passing Model
- Addressing
- Synchronization
- Example of IPC systems

- To introduce an alternative solution (to shared memory) for process cooperation
- To show pros and cons of message passing vs. shared memory
- To show some examples of message-based communication systems

- Message system – processes communicate with each other without resorting to shared variables.
- IPC facility provides two operations:
  - **send**(*message*) – fixed or variable message size
  - **receive**(*message*)
- If  $P$  and  $Q$  wish to communicate, they need to:
  - establish a *communication link* between them
  - exchange messages via send/receive
- The communication link is provided by the OS

## Physical implementation

- Single-processor system
  - Shared memory
- Multi-processor systems
  - Hardware bus
- Distributed systems
  - Networking System + Communication networks

## Logical properties

- Can a link be associated with more than two processes?
- How many links can there be between every pair of communicating processes?
- What is the capacity of a link?
- Is the size of a message that the link can accommodate fixed or variable?
- Is a link unidirectional or bi-directional?



# Implementation Issues



## Other Aspects

- Addressing
- Synchronization
- Buffering

- Message Passing Model
- **Addressing**
- Synchronization
- Example of IPC systems



- Processes must name each other explicitly.
- Symmetric scheme
  - **send** ( $D, message$ ) – send a message to process  $D$
  - **receive**( $S, message$ ) – receive a message from process  $S$
- Logical properties
  - A communication link exists between exactly two process
  - Links are established automatically
  - Links are usually FIFO

## ■ Asymmetric scheme

- **send** ( $D$ ,  $message$ ) – send a message to process  $D$
- **receive**( $proc$ ,  $message$ ) - receive a message from any process  $proc$

- Messages are sent/received through **mailboxes**
  - shared data structures where messages are queued temporarily. Sometimes referred to as **ports**
- Processes can communicate only if they share a mailbox
  - Each mailbox has a unique id
  - Processes can communicate only if they share a mailbox
- Primitives are defined as:
  - send**(*mb*, *message*) – send a message to mailbox *A*
  - receive**(*mb*, *message*) – receive a message from mailbox *mb*

## ■ Operations

- create a new mailbox
- send and receive messages through mailbox
- destroy a mailbox

## ■ Properties of communication link

- Link established only if processes share a common mailbox
- A link may be associated with many processes
- Each pair of processes may share several communication links
- Link may be unidirectional or bi-directional

## ■ Relationships

- One-to-one (private communication)
- Many-to-one (client-server communication)
- Many-to-many (multicast communication)

- Message Passing Model
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- **Synchronization**
- Example of IPC systems

- **Send operations may be**
  - **Synchronous**
  - **Asynchronous**
  
- **Receive operations may be**
  - **Blocking**
  - **Non-blocking**

- Blocking send, blocking receive
  - Rendez-vous between sender and receiver
  
- Non-blocking send, blocking receive
  - Most useful combination (used by servers)
  - Variations: receive with timeout, select, proactive test
  
- Non-blocking send, Non-blocking receive
  - Neither party is required to wait

- Queue of messages attached to the link; implemented in one of three ways.
  - 1) Zero capacity – 0 messages  
Sender must wait for receiver (in fact, this introduces a rendezvous).
  - 2) Bounded capacity – finite length of  $n$  messages  
Sender must wait if the link full.
  - 3) Unbounded capacity – infinite length  
Sender never waits.



```
Mailbox mb;
```

```
Process Producer {  
  while (TRUE) {  
    // message in nextProduced  
    send(mb, nextProduced);  
  }  
}
```

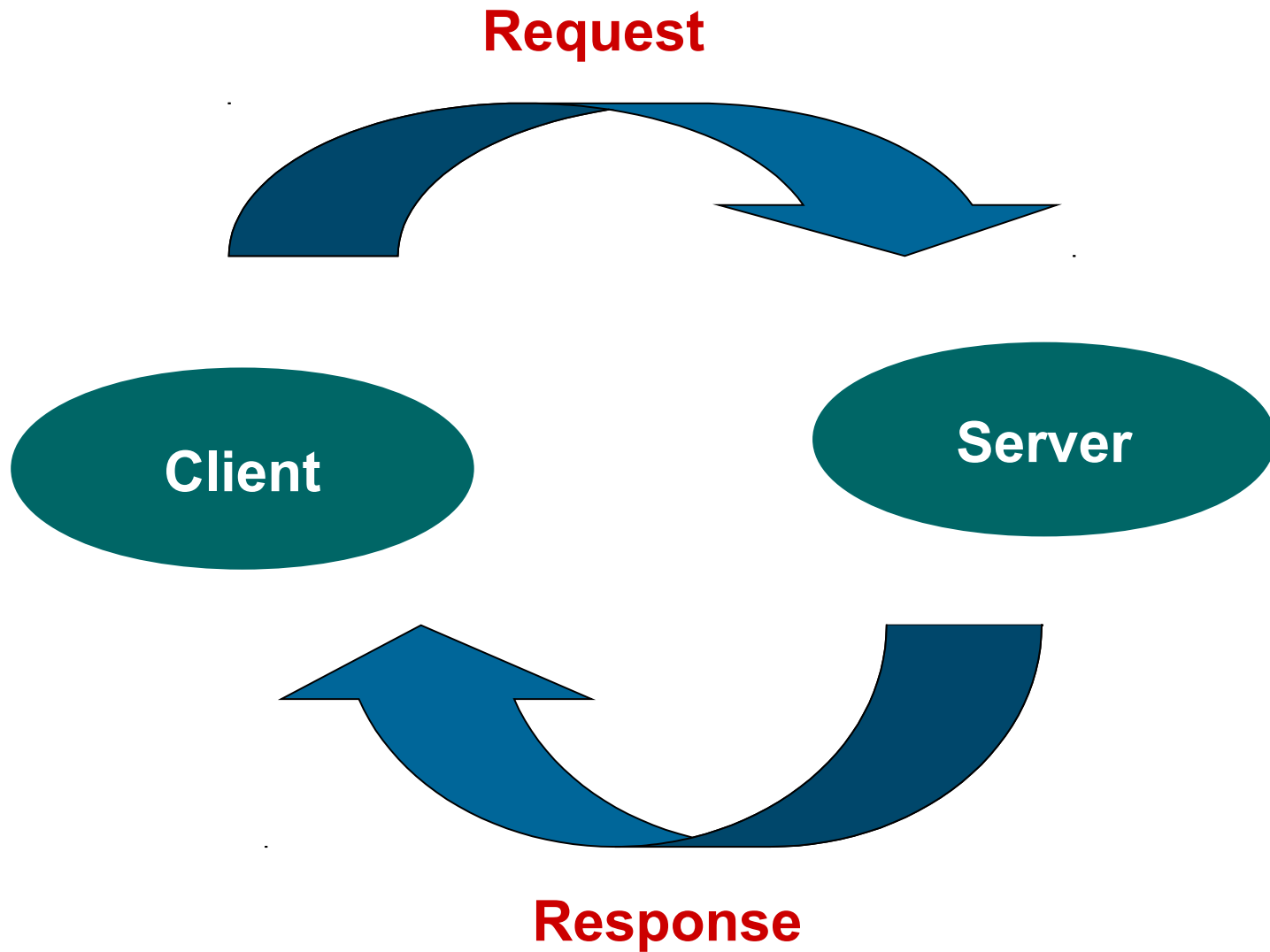
```
Process Consumer {  
  while (TRUE) {  
    receive(mb, msg);  
    // consume message  
  }  
}
```

Mailbox mb1, mb2;

```
Process Producer {  
  while (TRUE) {  
    // message in nextProduced  
    receive(mb2, ack);  
    send(mb1, nextProduced);  
  }  
}
```

```
Process Consumer {  
  while (TRUE) {  
    send(mb2, READY);  
    receive(mb1, msg);  
    // consume message  
  }  
}
```

- Message Passing Model
- Addressing
- Synchronization
- Client-Server Model



# Questions?

